

New Architectures for a New Biology

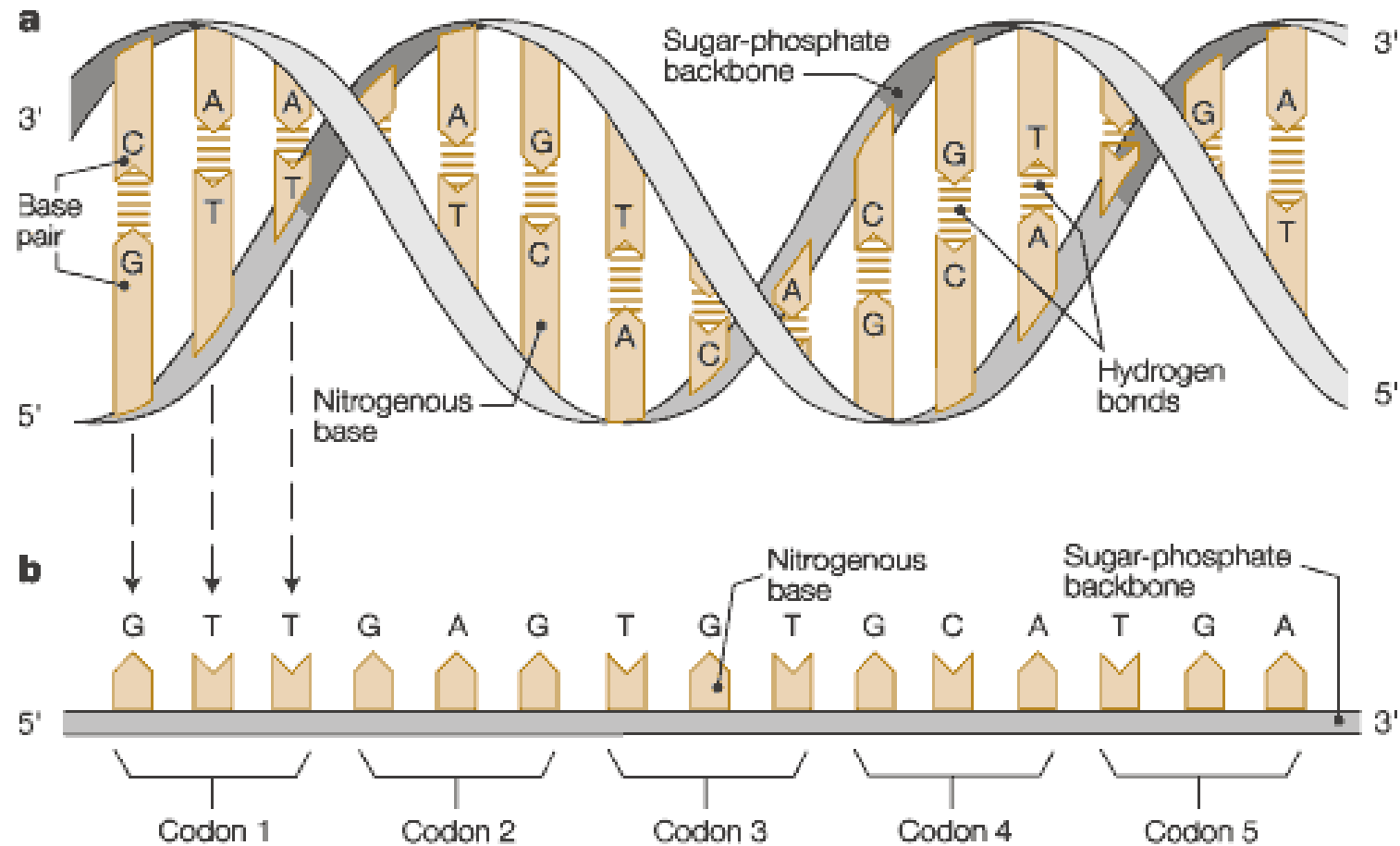
Martin M. Deneroff
deneroff@deshaw.com

D. E. Shaw Research, LLC



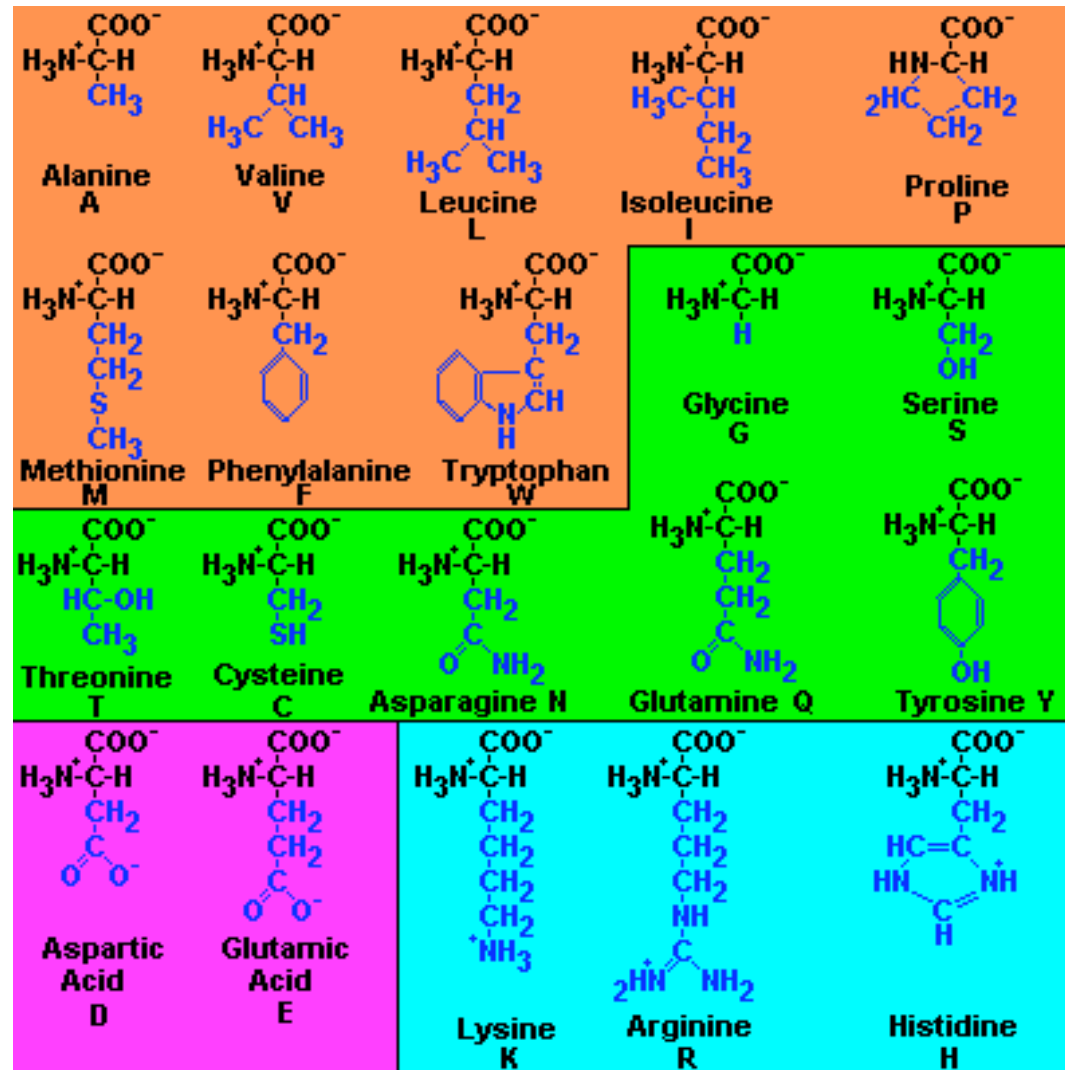
Background (A Bit of Basic Biochemistry)

DNA Codes for Proteins

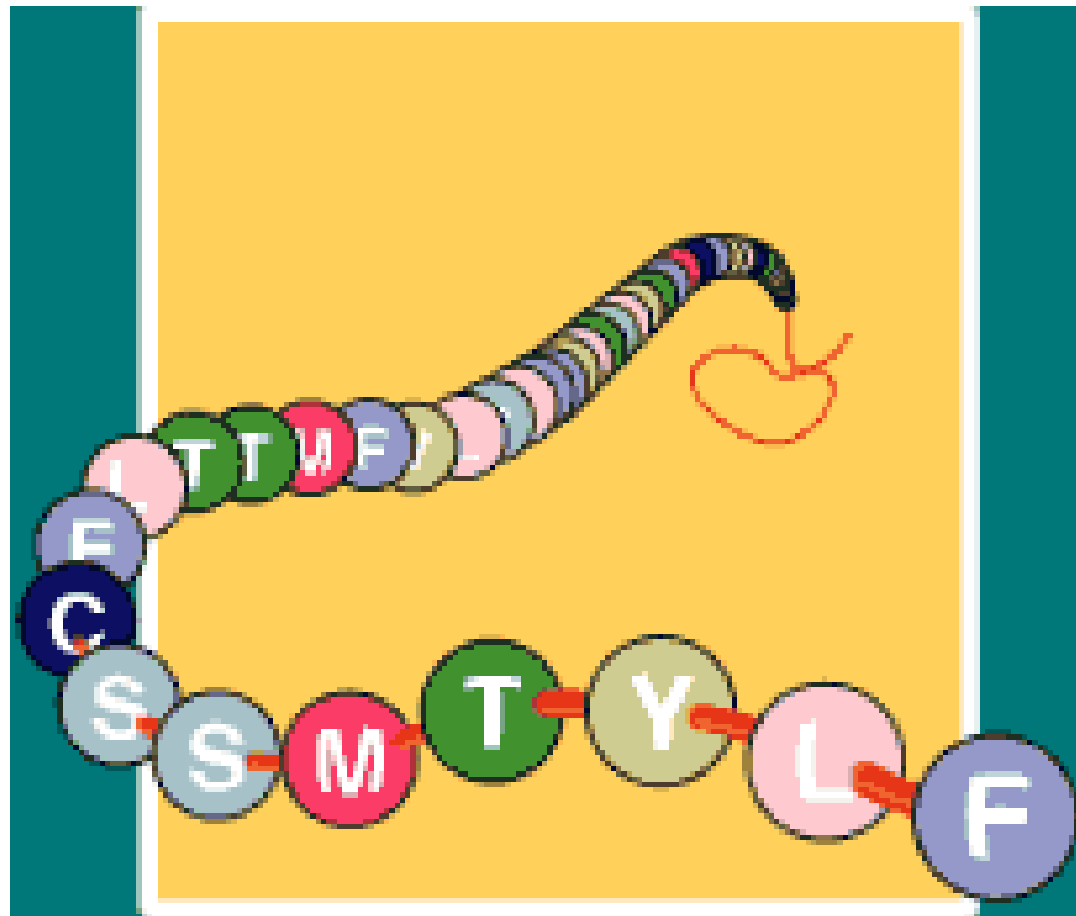


Source: *Molecular Biology of the Cell*, Garland Publishing, Inc., New York, 1994

The 20 Amino Acids

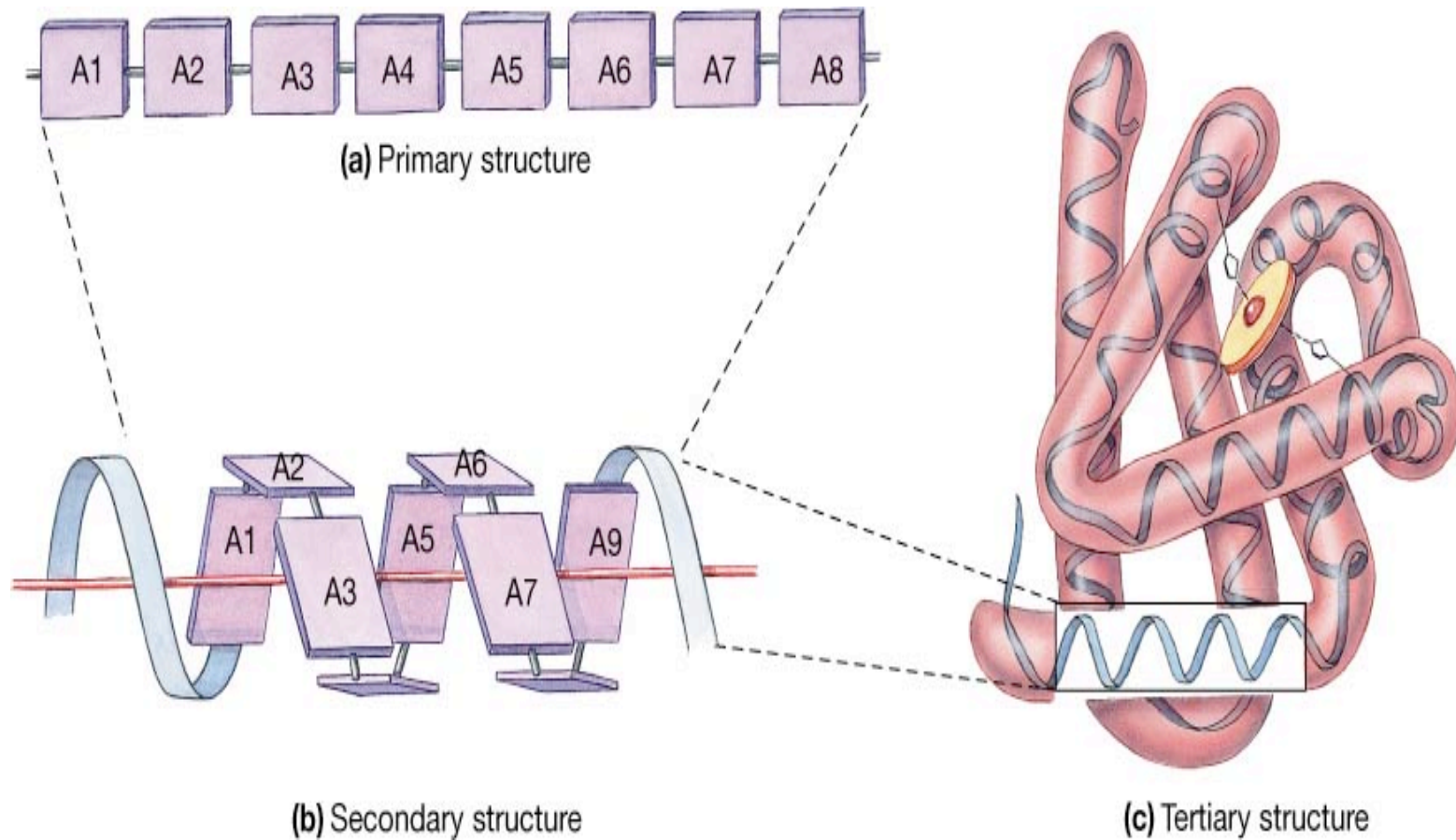


Polypeptide Chain



Source: www.yourgenome.org

Levels of Protein Structure



Source: Robert Melamede, U. Colorado

What We Know and What We Don' t

- Decoded the genome
- Don' t know most protein structures
 - Especially membrane proteins
- No detailed picture of what most proteins do
- Don' t know how everything fits together into a working system

We Now Have The Parts List ...

SECTION 7 PARTS LIST

7.1 BOARD A-I

REFERENCE	ARP PART NUMBER	ARP/MFG NUMBER
A1, 2	5601801	A-2801-008A/SL 19988
A3, 4	5601901	A-2801-009/SL19986
Q6,8	1303901	IMF3958
Q2,3	1301701	2N5172
Q9	5600401	A2802-014-1
Q1,4,5	1302801	2N6076
CR1-6	1200301	1N4148
P2	1001203	B2801-006-1B
P1	5701801	B-2801-010-1A
T3,T4	1000903	U201R251B
T1	1000904	R201R102B
T2	1000913	U201R103B
C8	1100901	WCR1P47
C2	1100702	150D406X9010B
C4,5	1100608	G-0-001-G-10-0
S1	1900801	02-481-0001
S2	1902401	02-481-0006

7.2 BOARD B-I

REFERENCE	ARP PART NUMBER	ARP/MFG NUMBER
A1,2,	5601801	A2801-008A
A3	5601501	A4024-006-2B
Z1,2	5602001	A2803-002A
Q1,9,10,16,17,18	1301701	2N5172
Q7,14	1302801	2N6076
Q4/5,Q11/12	7502600	APL4027-008
Q2,8,15	1302501	2N5461

REFERENCE	ARP PART NUMBER	ARP/MFG NUMBER
Q3	5600201	A2803-003-1B
Q6,13	5600202	A2803-003-2B
CR1-3,5-12	1200301	1N4148
CR4	1200102	1N34
C12,16	1101201	DM-15-681K
C10,11	1100612	Tag-00-10/35-50/20
R32,44	1000105	SA-21
P16	5700701	B2801-006-1D
P5,6,7,10,11,	5700702	B2801-006-2B
P1,2,3,4,8,9,12,		
13,14,15	5700703	B2801-006-3B
T1,4,7	1000909	U201R103B
T2,3,5,6	1000915	U201R104B
S1-11	1902401	01-481-0006

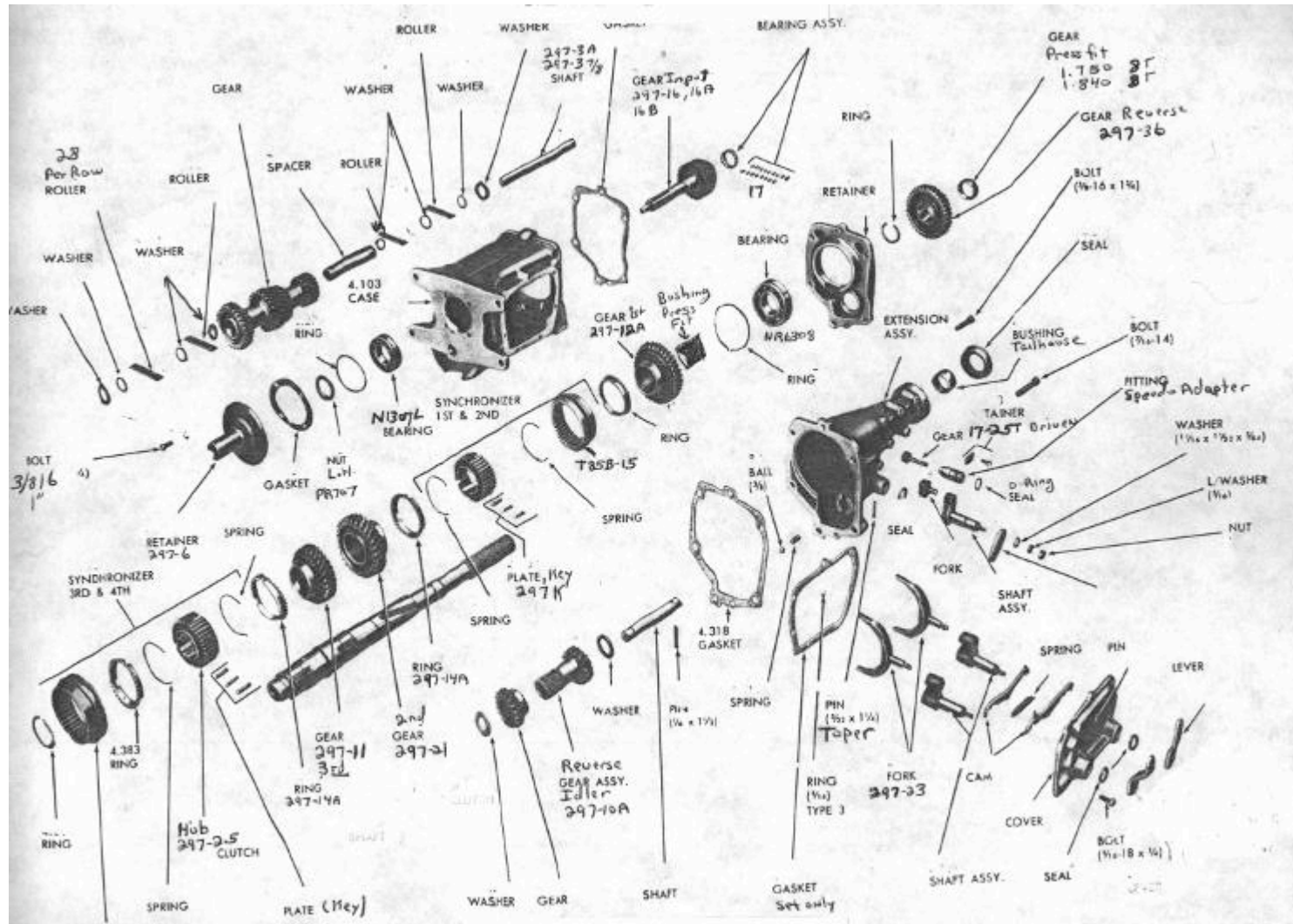
7.3 BOARD C-I

REFERENCE	ARP PART NUMBER	ARP/MFG NUMBER
M1	4023	
A1	5601901	A-2801-009-1
A2	5601501	B4023-006-2B
Q12	1304601	TZ81
Q2,3,4,6,8,		
10,13,16,18	1301701	2N5172
Q2,5,7,9,11,		
14,15,17	1302801	2N6076
CR1-22	1200301	1N4148
C7,8	1100602	TAG-00-3.3/20-10/10

But We Don't Know What the Parts Look Like ...

	 D-F S-S			 D-F S-S	 D-F S-S	 D-F S-S	 D-F S-S	 D-F S-S	 S-S
スタビライザー ブレード No.H3104 ●950 Stabilizer Blade	ピッチスライダ ベアリング No.H3106 ●800 10 x 15 x 3mm Ball Bearing	ロッドエンドセット No.H3108 ●300 Rod End Set	エレベーターリンク No.H3110 ●100 Elevator Link	エルロンピッチレバ ーセット (SR) No.H3120 ●900 Aileron Pitch Lever Set (SR)	ミキシングベース No.H3304 ●2,000 Mixing Base	メインローター (4D) No.H3305 ●3,800 Main Rotor (4D)	スターターベアリング ケース No.H3306 ●900 Starter Bearing Case	ミキシングレバ ーセット (D) No.H3307 ●1,800 Mixing Lever Set (D)	スタビライザーシー ソー (S) No.H3308 ●1,000 Stabilizer Seesaw (S)
		 S-S	 D-F S-S	 D-F S-S	 S-S	 S-S	 S-S	 S-S	 S-S
テールピッチレバ ーセット (SR) No.H3123 ●700 Tail Pitch Lever Set (SR)	テールブーム (SR) No.H3126 ●900 Tail Boom (SR)	シャフトガイド 2mm No.H3130 ●500 Shaft Guide (2mm)	スラストベアリング No.H3241 ●2,200 Thrust Bearing Set	スワッシュプレート (SX) No.H3242 ●4,500 Swashplate (SX)	スペーサーセット (S) No.H3310 ●500 Spacer Set (S)	フェザリングシャフト セット (S) No.H3311 ●600 Feathering Shaft (S)	シーソーダンパー No.H3312 ●400 Stabilizer Seesaw Damper	メインローターヘッド (S) No.H3313 ●900 Main Rotor Head (S)	3mmストッパー No.H3314 ●500 3mm Stopper
 S-S	 D-F S-S	 D-F S-S	 D-F	 D-F	 S-S	 S-S			
メインギヤハウジング No.H3272 ●1,200 Main Gear Housing	シャフトガイド (SR-X) No.H3277 ●900 Shaft Guide	テールガイドパイプ (SR-X) No.H3278 ●800 Tail Guide Pipe (SR-X)	スタビライザー シーソー (F) No.H3301 ●800 Stabilizer Seesaw	フェザリングシャフト セット (F) No.H3302 ●1,500 Feathering Shaft Set	ミキシングベース No.H3316 ●700 Mixing Base	メインローター (4S) No.H3317 ●2,900 Main Rotor (4S)	デカール No.H3318 ●800 Decal	リンクージセット No.H3319 ●1,200 Linkage Set	メインローター グリップ No.H3320 ●900 Main Rotor Grip

Or How They Fit Together ...



Or How The Whole Machine Works



How Can We Get There?

Two major approaches:

- **Experiments**

- Wet lab
- Hard, since everything is so small

- **Simulation**

- Simulate:
 - How proteins fold (structure, dynamics)
 - How proteins interact with
 - Other proteins
 - Nucleic acids
 - Drug molecules
- Gold standard: Molecular dynamics (MD)



Molecular Dynamics

Molecular Dynamics

Divide time into discrete time steps

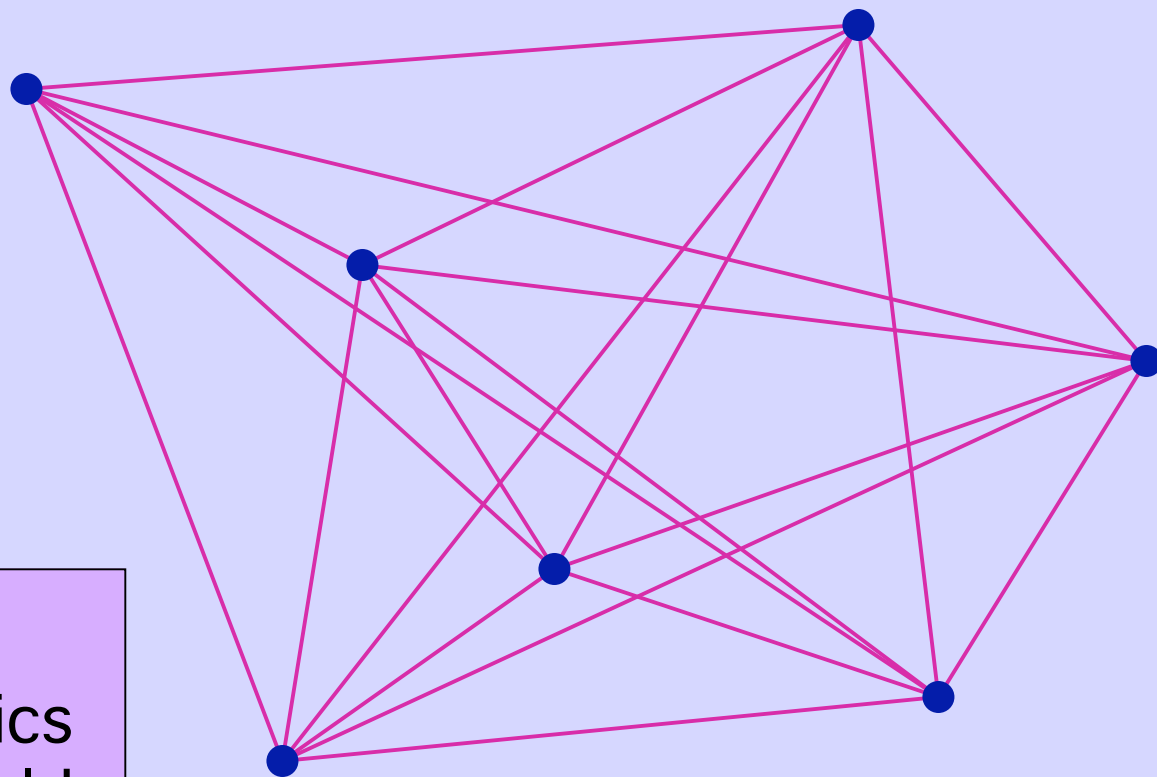
$t \longrightarrow$

~1 fs time
step

Molecular Dynamics

Calculate forces

Molecular mechanics
force field



Molecular Dynamics

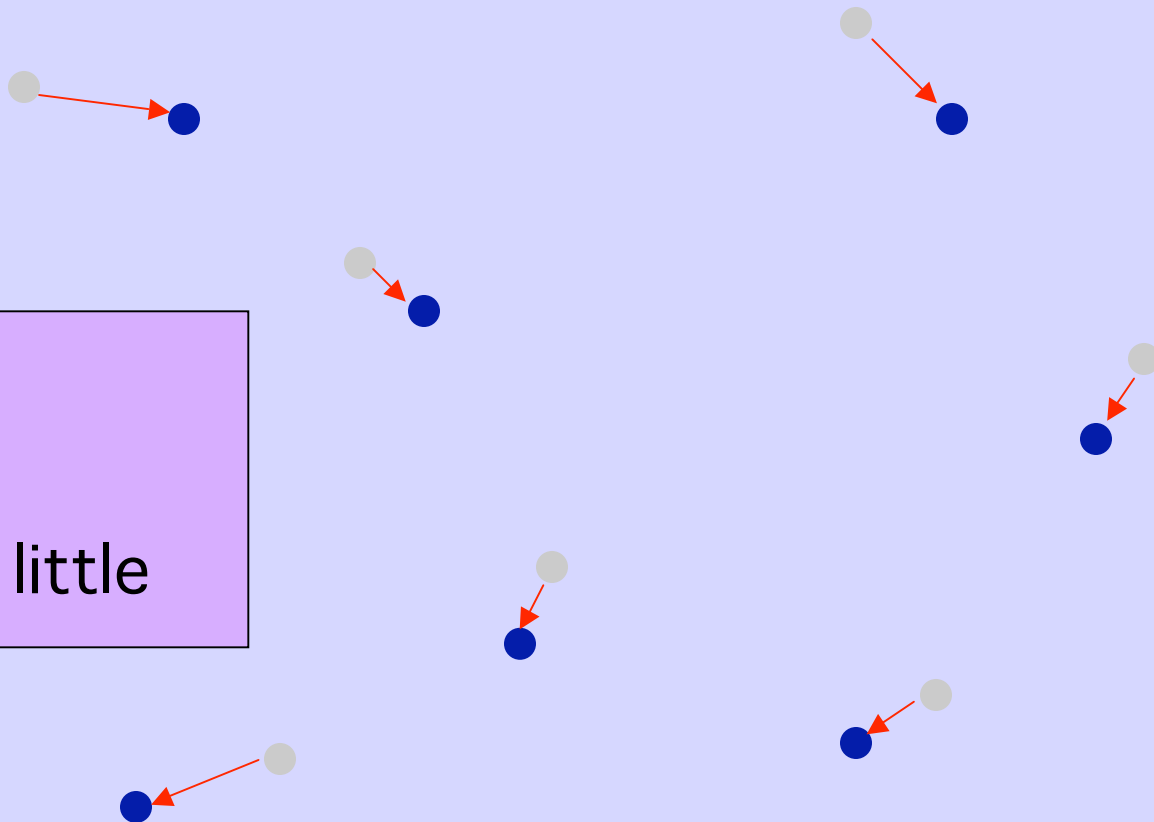
Move atoms



Molecular Dynamics

Move atoms

... a little
bit



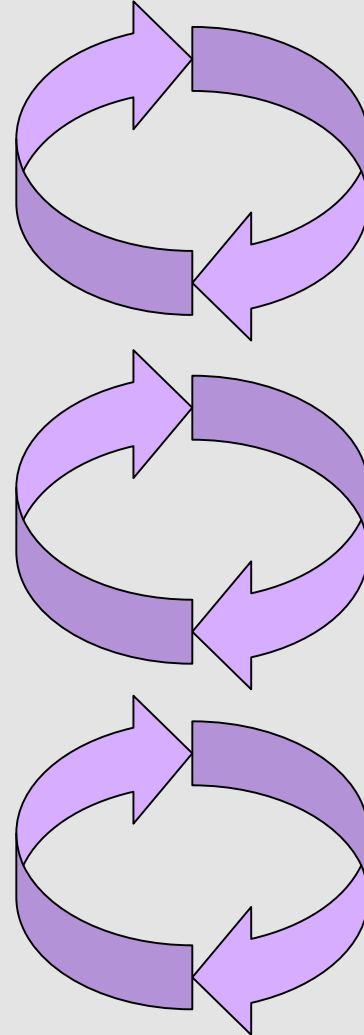
Molecular Dynamics

Iterate

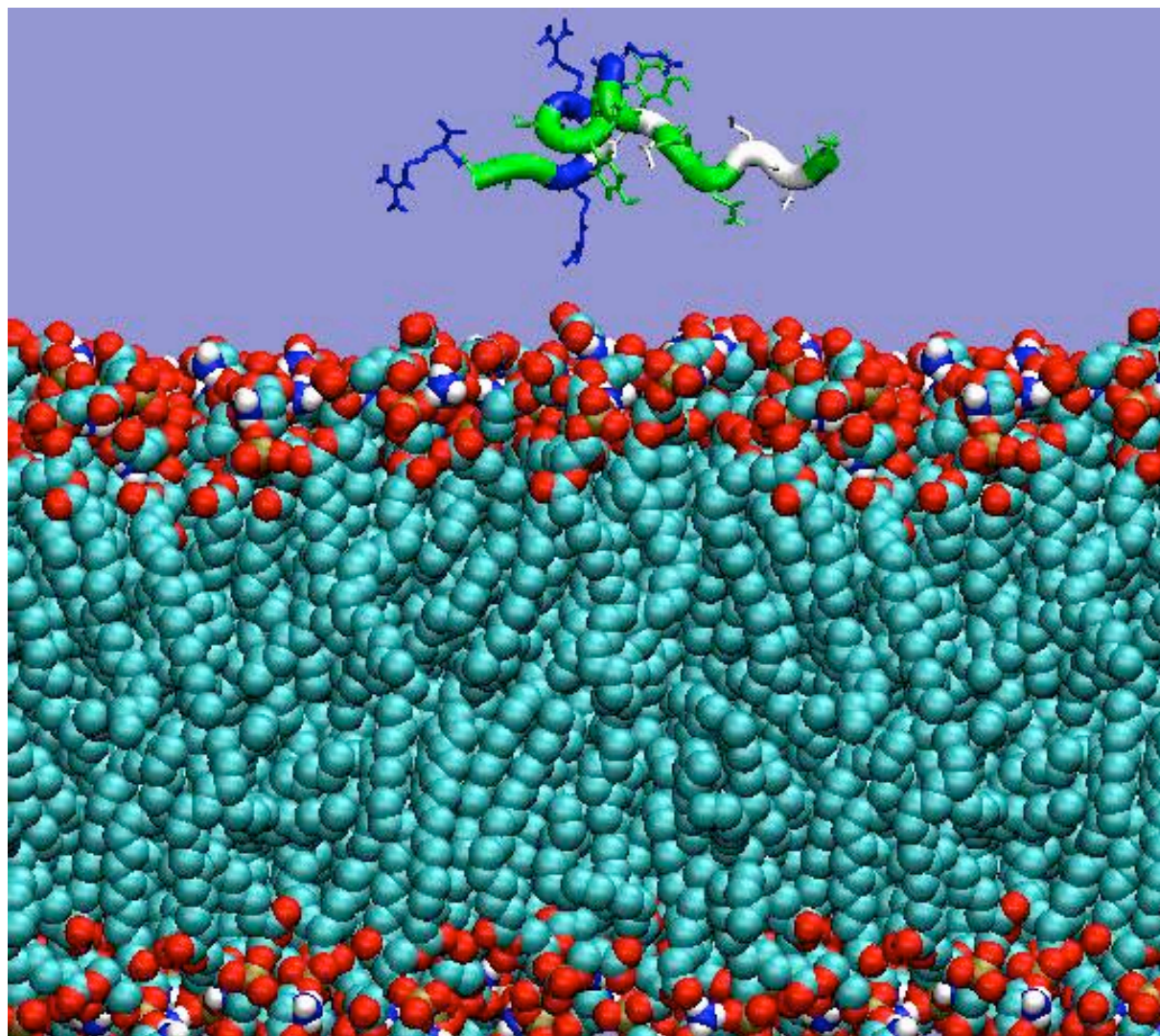
... and iterate

... and iterate

Integrate Newton's
laws of motion



Example of an MD Simulation



Main Problem With MD

Too slow!

Example I just showed:

- 2 ns simulated time
- 3.4 CPU-days to simulate



Goals and Strategy

Thought Experiment

- What if MD were
 - _ Perfectly accurate?
 - _ Infinitely fast?
- Would be easy to perform
arbitrary computational experiments
 - _ Determine structures by watching them form
 - _ Figure out what happens by watching it happen
 - _ Transform measurement into data mining

Two Distinct Problems

Problem 1: Simulate many short trajectories

Problem 2: Simulate one long trajectory

Simulating Many Short Trajectories

- Can answer surprising number of interesting questions
- Can be done using
 - _ Many slow computers
 - _ Distributed processing approach
 - _ Little inter-processor communication
- E.g., Pande' s *Folding at Home* project

Simulating One Long Trajectory

- Harder problem
- Essential to elucidate many biologically interesting processes
- Requires a single machine with
 - _ Extremely high performance
 - _ Truly massive parallelism
 - _ Lots of inter-processor communication

DESRES Goal

- Single, millisecond-scale MD simulations (long trajectories)
 - _ Protein with 64K or more atoms
 - _ Explicit water molecules
- Why?
 - _ That's the time scale at which many biologically interesting things start to happen

Protein Folding

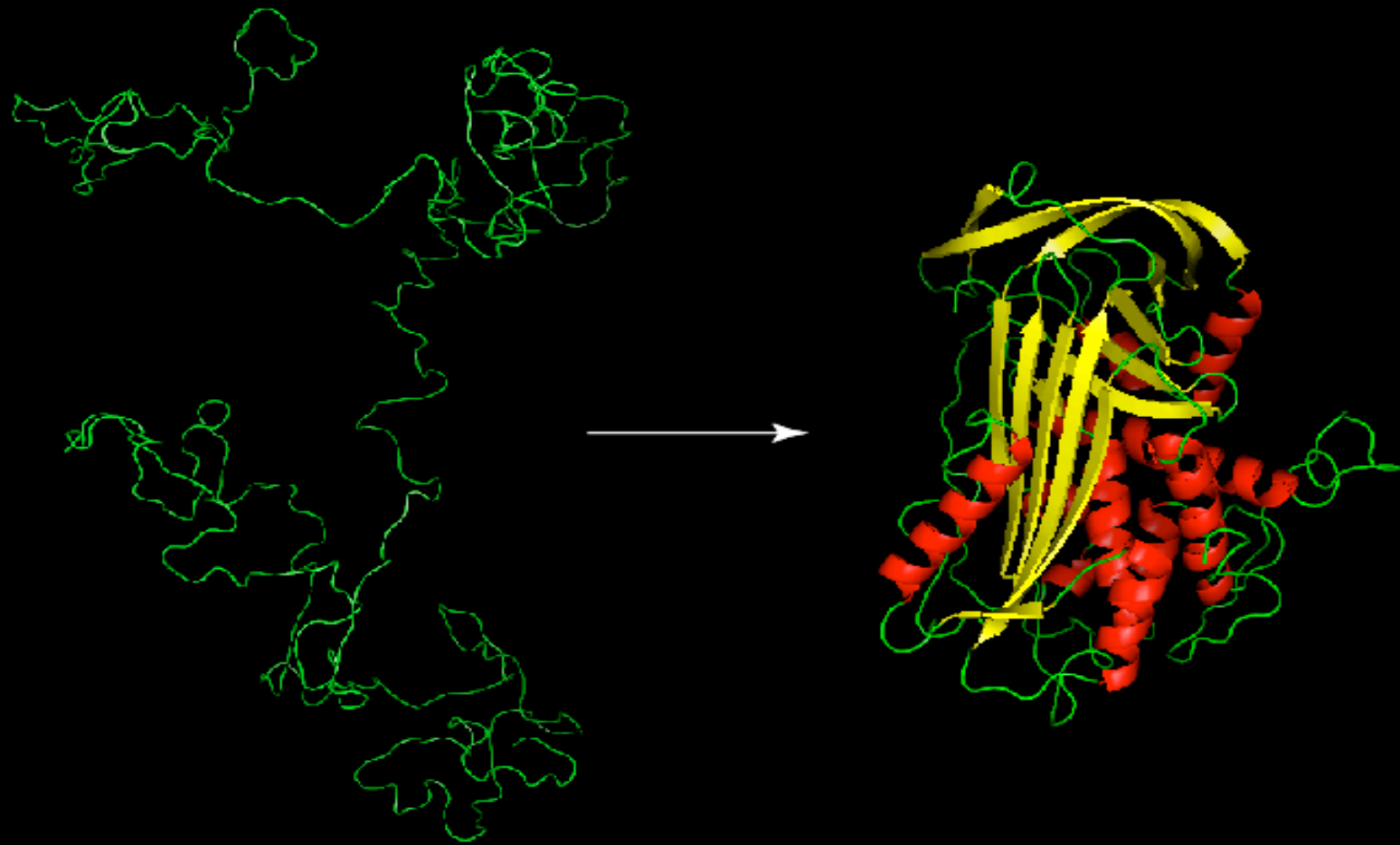


Image: Istvan Kolossvary & Annabel Todd,
D. E. Shaw Research

Interactions Between Proteins

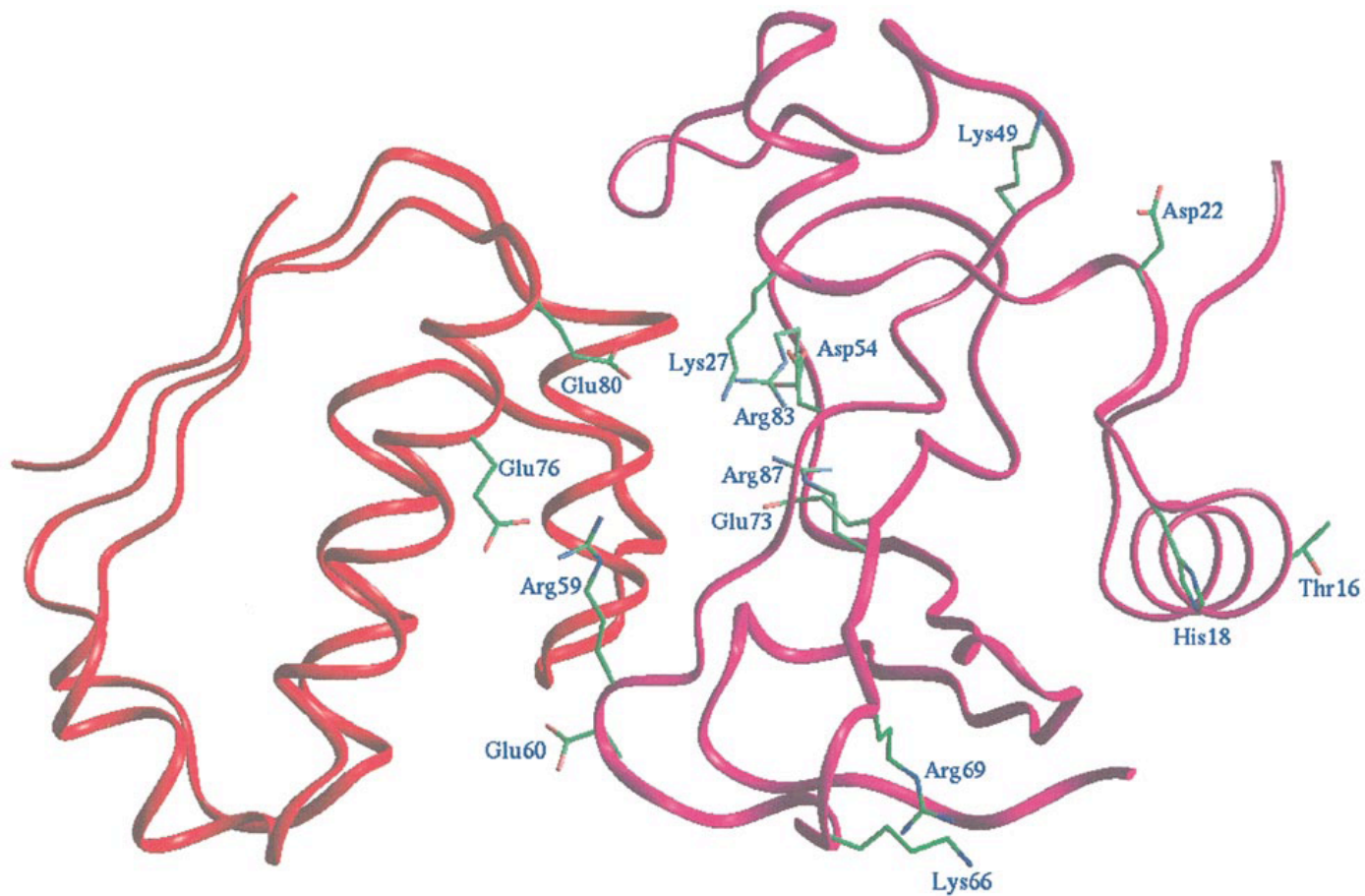


Image: Vijayakumar, et al., *J. Mol. Biol.* 278, 1015 (1998)

Binding of Drugs to their Molecular Targets

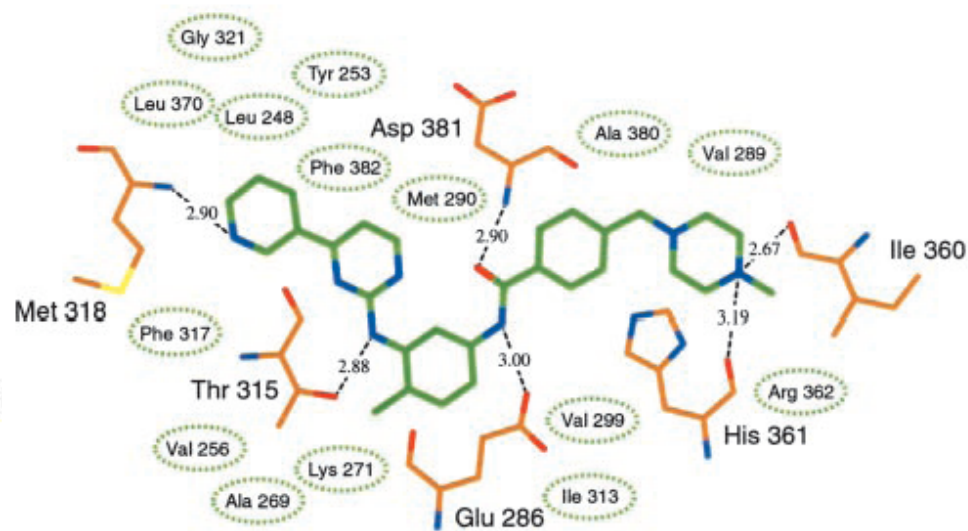
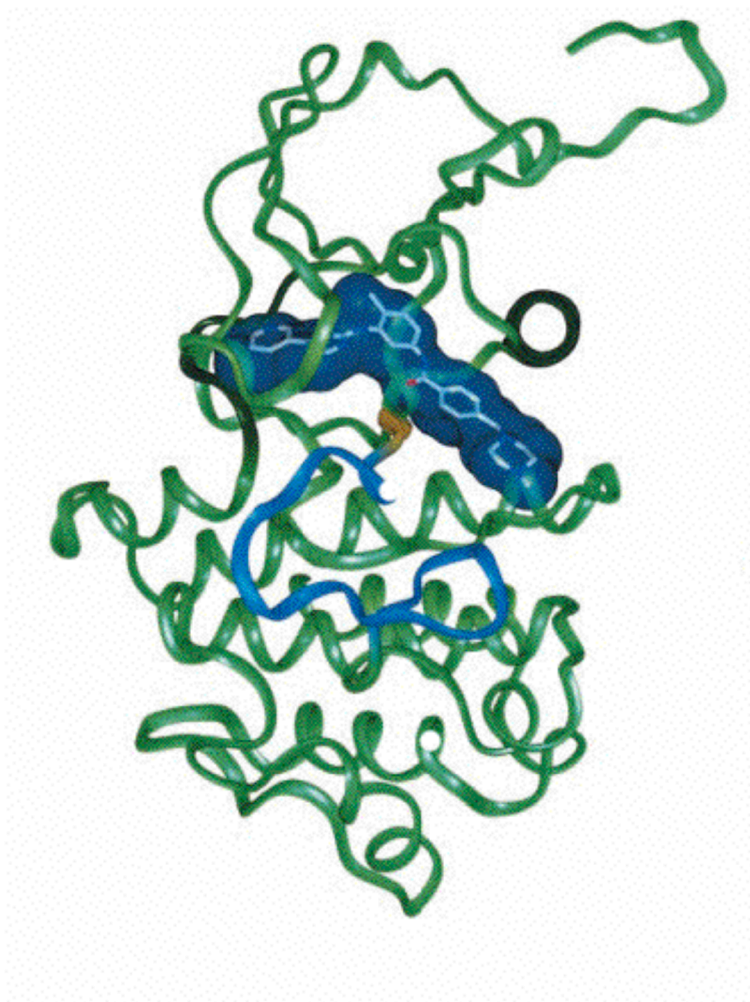


Image: Nagar, et al., *Cancer Res.* 62, 4236 (2002)

Mechanisms of Intracellular Machines

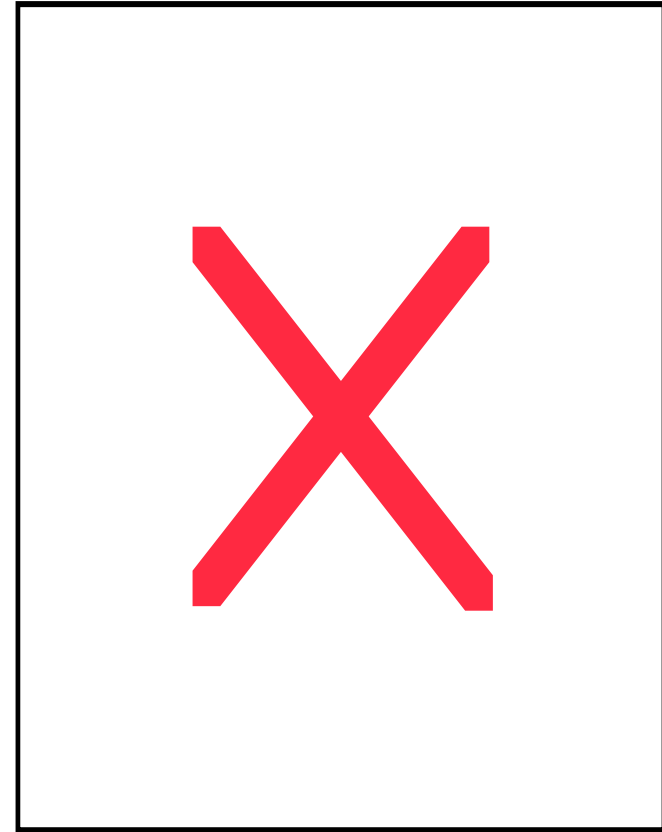
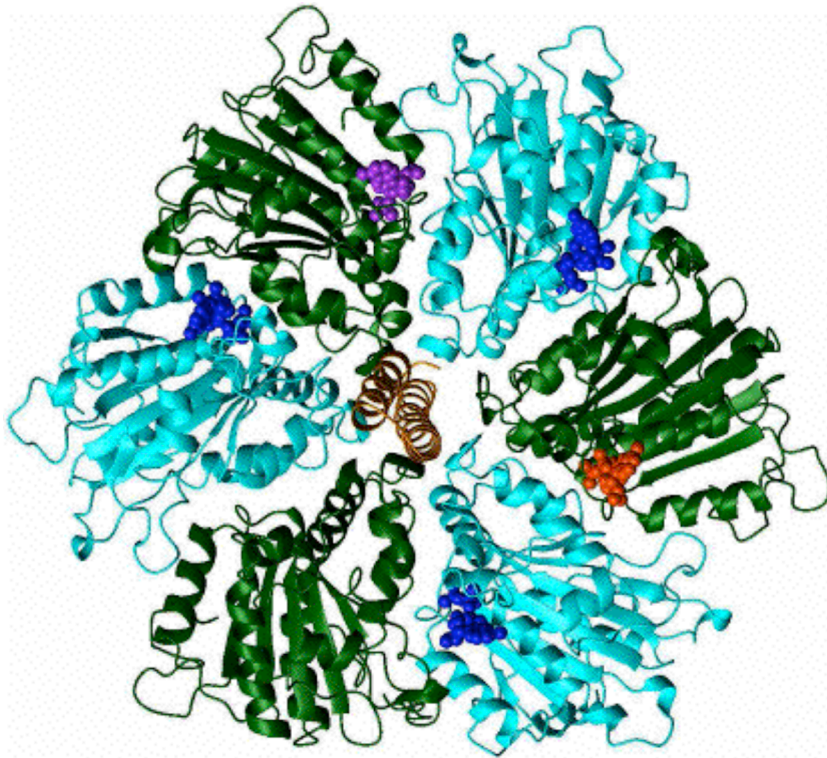
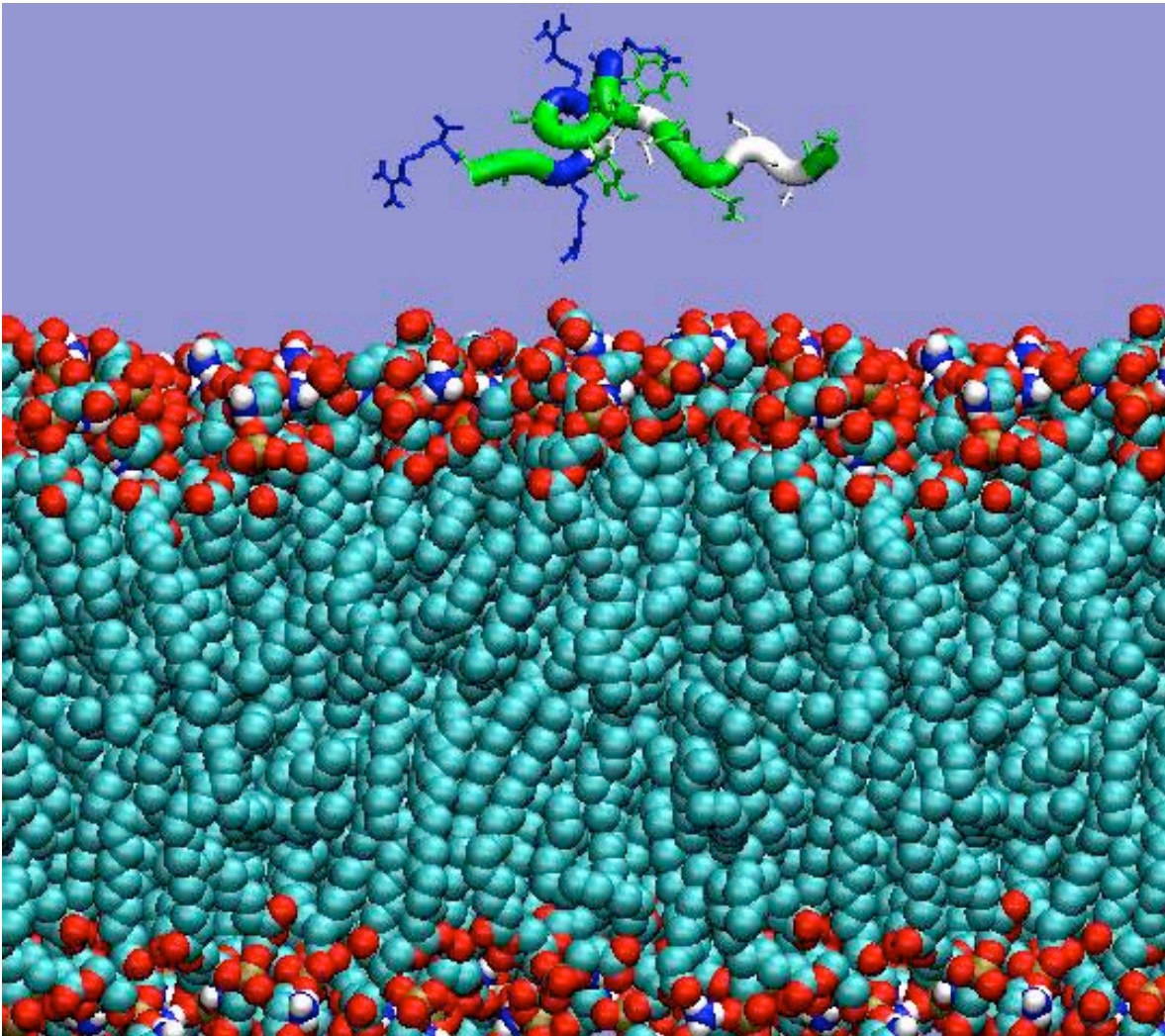


Image: H. Grubmüller, in Attig, et al. (eds.), Computational Soft Matter (2004)

What Will It Take to Simulate a Millisecond?

- We need an **enormous** increase in speed
 - _ Current (single processor): $\sim 100 \text{ ms} / \text{fs}$
 - _ Goal will require $< 10 \mu\text{s} / \text{fs}$
- Required speedup:
 - $> 10,000\times$ faster than current single-processor speed
 - $\sim 1,000\times$ faster than current parallel implementations
- *Can't accept $> 10,000\times$ the power (~ 5 Megawatts)!*

Target Simulation Speed



3.4 days today
(one processor)

~ 13 seconds on
our machine
(one segment)

Molecular Mechanics Force Field

Stretch

Bend

Torsion

Bonded

—

Electrostatic

— —

Van der Waals

Non-
Bonded

What Takes So Long?

- Inner loop of force field evaluation looks at all *pairs* of atoms (within distance R)
- On the order of 64K atoms in typical system
- Repeat $\sim 10^{12}$ times
- Current approaches too slow by several orders of magnitude
- What can be done?

Our Strategy

- New architectures

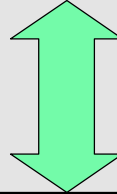
- _ Design a specialized machine
- _ Enormously parallel architecture
- _ Based on special-purpose ASICs
- _ Dramatically faster for MD, but less flexible
- _ Projected completion: 2008

- New algorithms

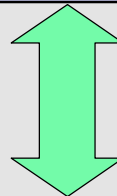
- _ Applicable to
 - Conventional clusters
 - Our own machine
- _ Scale to very large # of processing elements

Interdisciplinary Lab

Computational Chemists and Biologists



Computer Scientists and Applied Mathematicians



Computer Architects and Engineers



New Architectures

Alternative Machine Architectures

- Conventional cluster of commodity processors
- General-purpose scientific supercomputer
- Special-purpose molecular dynamics machine

Conventional Cluster of Commodity Processors

- Strengths:
 - _ Flexibility
 - _ Mass market economies of scale
- Limitations
 - _ Doesn't exploit special features of the problem
 - _ Communication bottlenecks
 - Between processor and memory
 - Among processors
 - _ Insufficient arithmetic power

General-Purpose Scientific Supercomputer

- E.g., IBM *Blue Gene*
- More demanding goal than ours
 - _ General-purpose scientific supercomputing
 - _ Fast for wide range of applications
- Strengths:
 - _ Flexibility
 - _ Ease of programmability
- Limitations for MD simulations
 - _ Expensive
 - _ Still not fast enough for our purposes

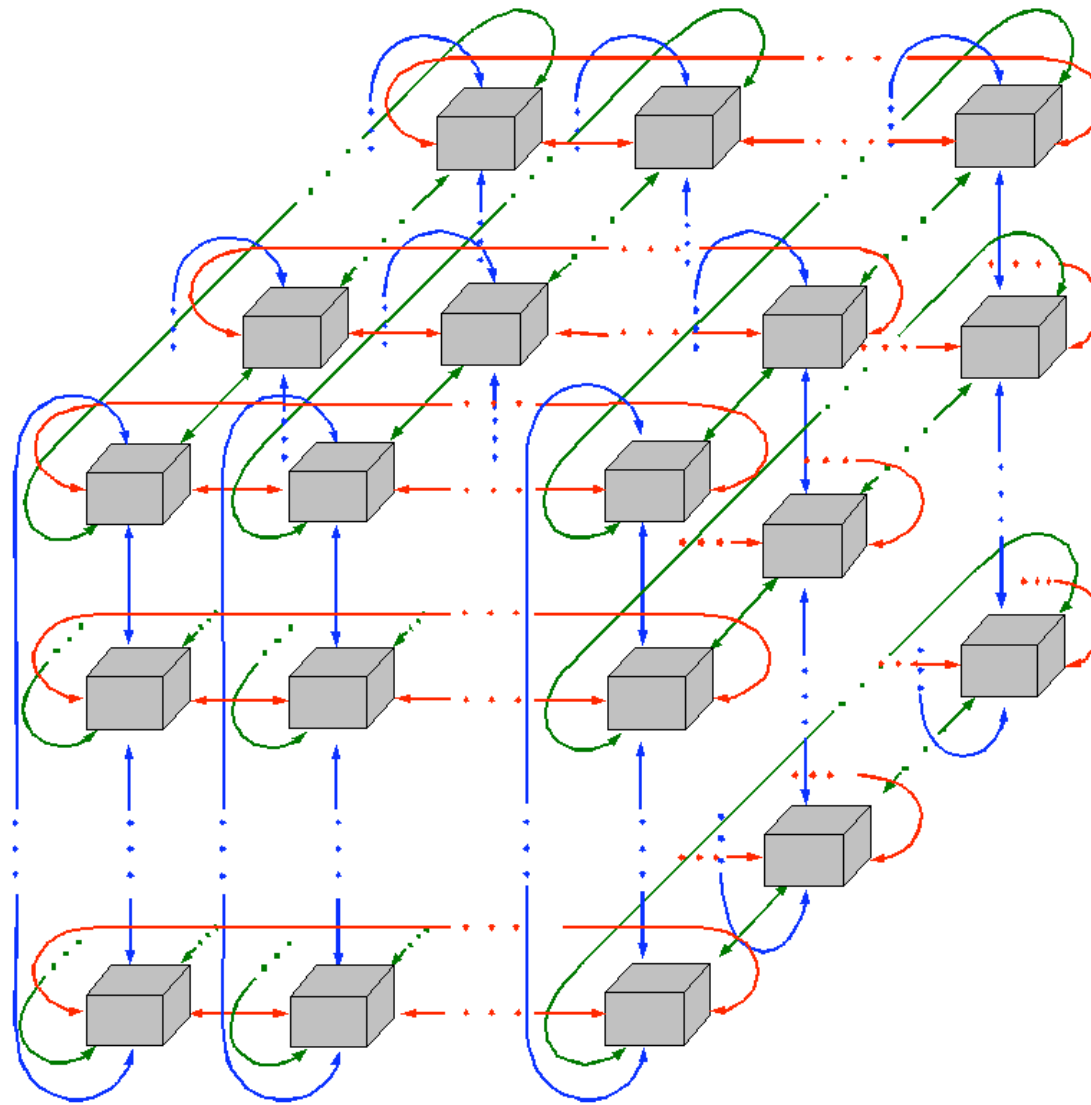
Anton: DESRES' Special-Purpose MD Machine

- Strengths:
 - _ Several orders of magnitude faster for MD
 - _ Excellent cost/performance characteristics
- Limitations:
 - _ Not designed for other scientific applications
 - They' d be difficult to program
 - Still wouldn' t be especially fast
 - _ Limited flexibility

Anton System-Level Organization

- Multiple segments (probably 8 in first machine)
- 512 nodes (each consists of one ASIC plus DRAM) per segment
 - _ Organized in an 8 x 8 x 8 toroidal mesh
- Each ASIC equivalent performance to roughly 500 general purpose microprocessors
 - _ ASIC power similar to a single microprocessor

3D Torus Network



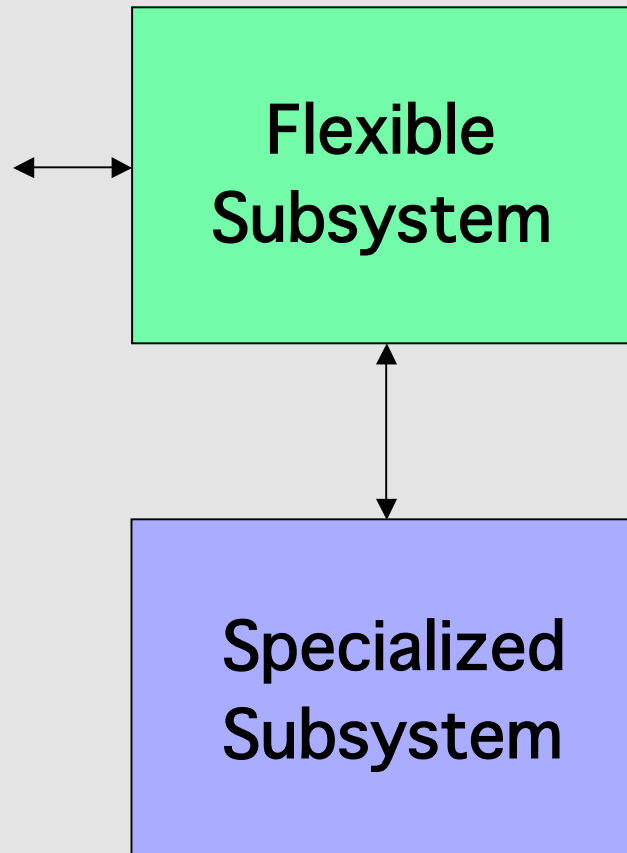
Why a 3D Torus?

- Topology reflects physical space being simulated:
 - _ Three-dimensional nearest neighbor connections
 - _ Periodic boundary conditions
- Bulk of communications is to near neighbors
 - _ No switching to reach immediate neighbors

Source of Speedup on Our Machine

- Judicious use of **arithmetic specialization**
 - _ Flexibility, programmability only where needed
 - _ Elsewhere, hardware tailored for speed
 - Tables and parameters, but not programmable
- Carefully **choreographed communication**
 - _ Data flows to just where it's needed
 - _ Almost never need to access off-chip memory

Two Subsystems on Each ASIC



- Programmable, general-purpose
 - Efficient geometric operations
 - Modest clock rate
-
- Pairwise point interactions
 - Enormously parallel
 - Aggressive clock rate

Where We Use Specialized Hardware

Specialized hardware (with tables, parameters)
where:

- Inner loop

- Simple, regular algorithmic structure

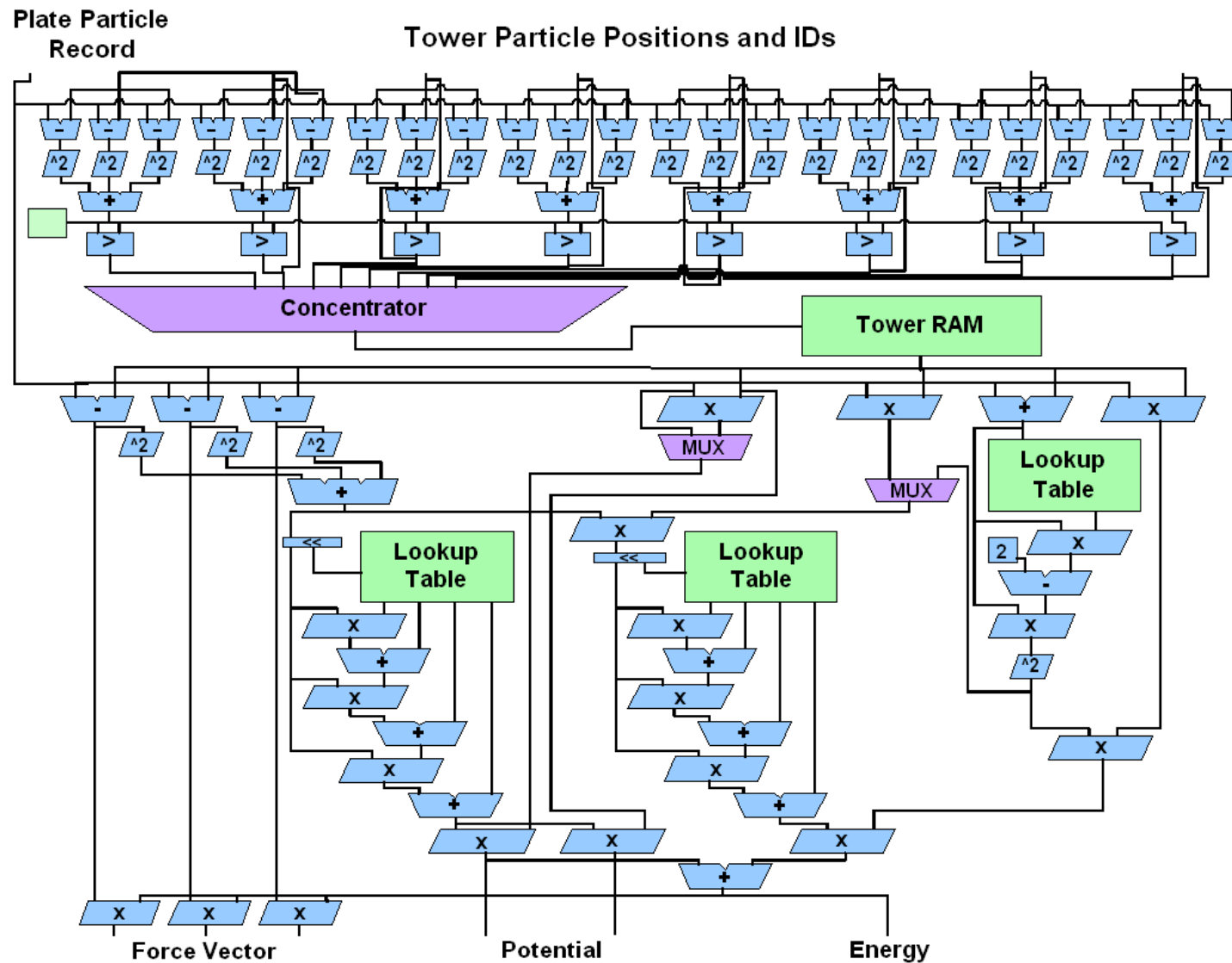
- Unlikely to change

Examples:

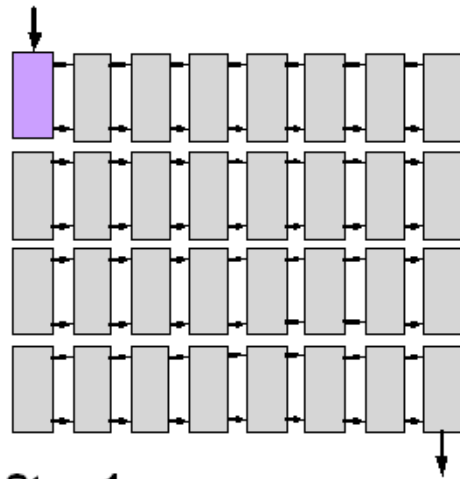
- Electrostatic forces

- Van der Waals interactions

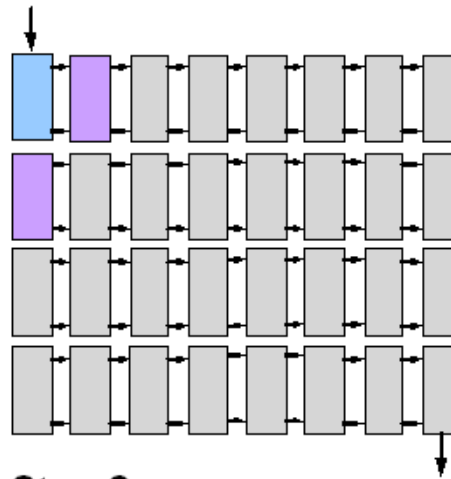
Example: Particle Interaction Pipeline (one of 32)



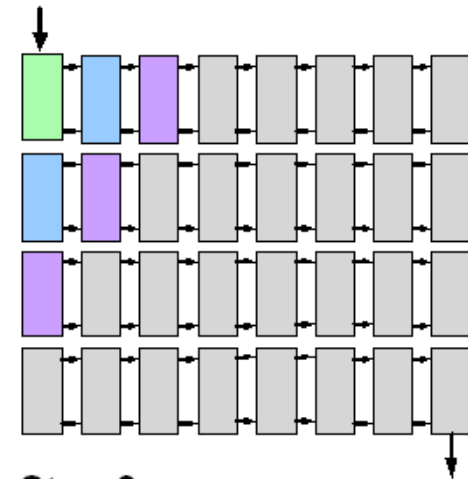
Array of 32 Particle Interaction Pipelines



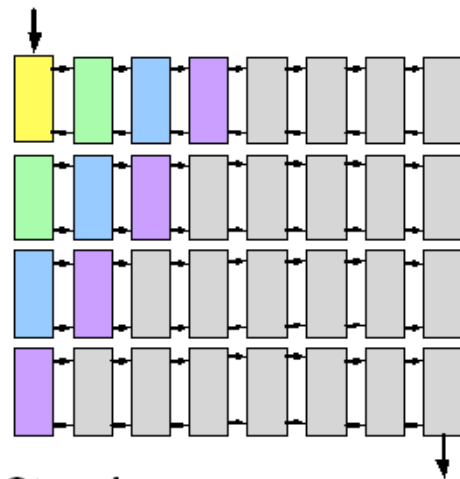
Step 1



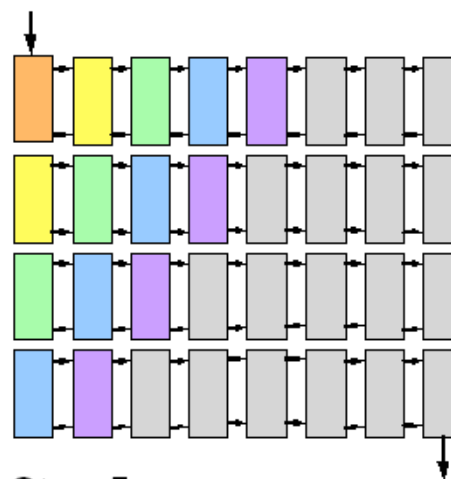
Step 2



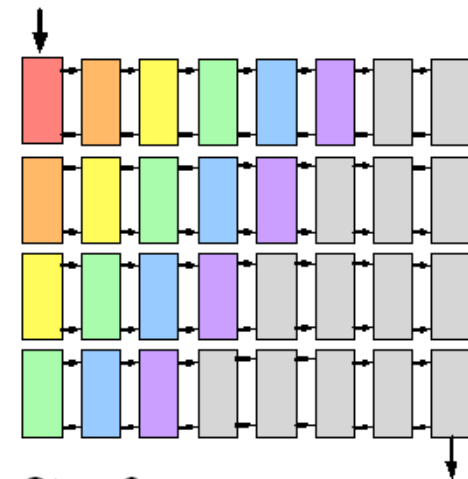
Step 3



Step 4



Step 5



Step 6

Advantages of Particle Interaction Pipelines

- Save area that would have been allocated to
 - _ Cache
 - _ Control logic
 - _ Wires
- Achieve extremely high arithmetic density
- Save time that would have been spent on
 - _ Cache misses,
 - _ Load/store instructions
 - _ Misc. data shuffling

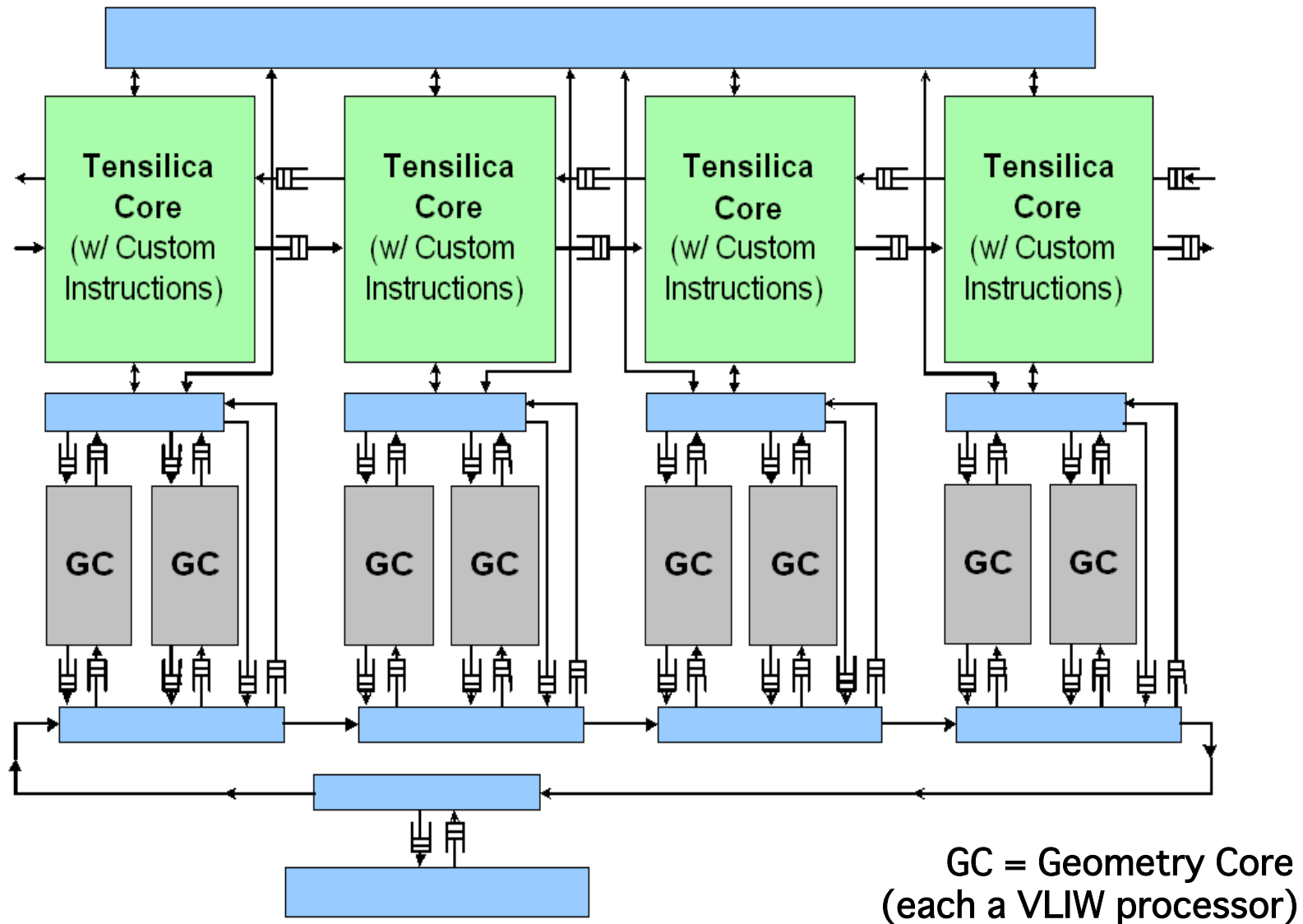
Where We Use Flexible Hardware

- _ Use programmable hardware where:
 - Algorithm less regular
 - Smaller % of total computation
 - E.g., local interactions (fewer of them)
 - More likely to change
- _ Examples:
 - Bonded interactions
 - Bond length constraints
 - Experimentation with
 - New, short-range force field terms
 - Alternative integration techniques

Forms of Parallelism in Flexible Subsystem

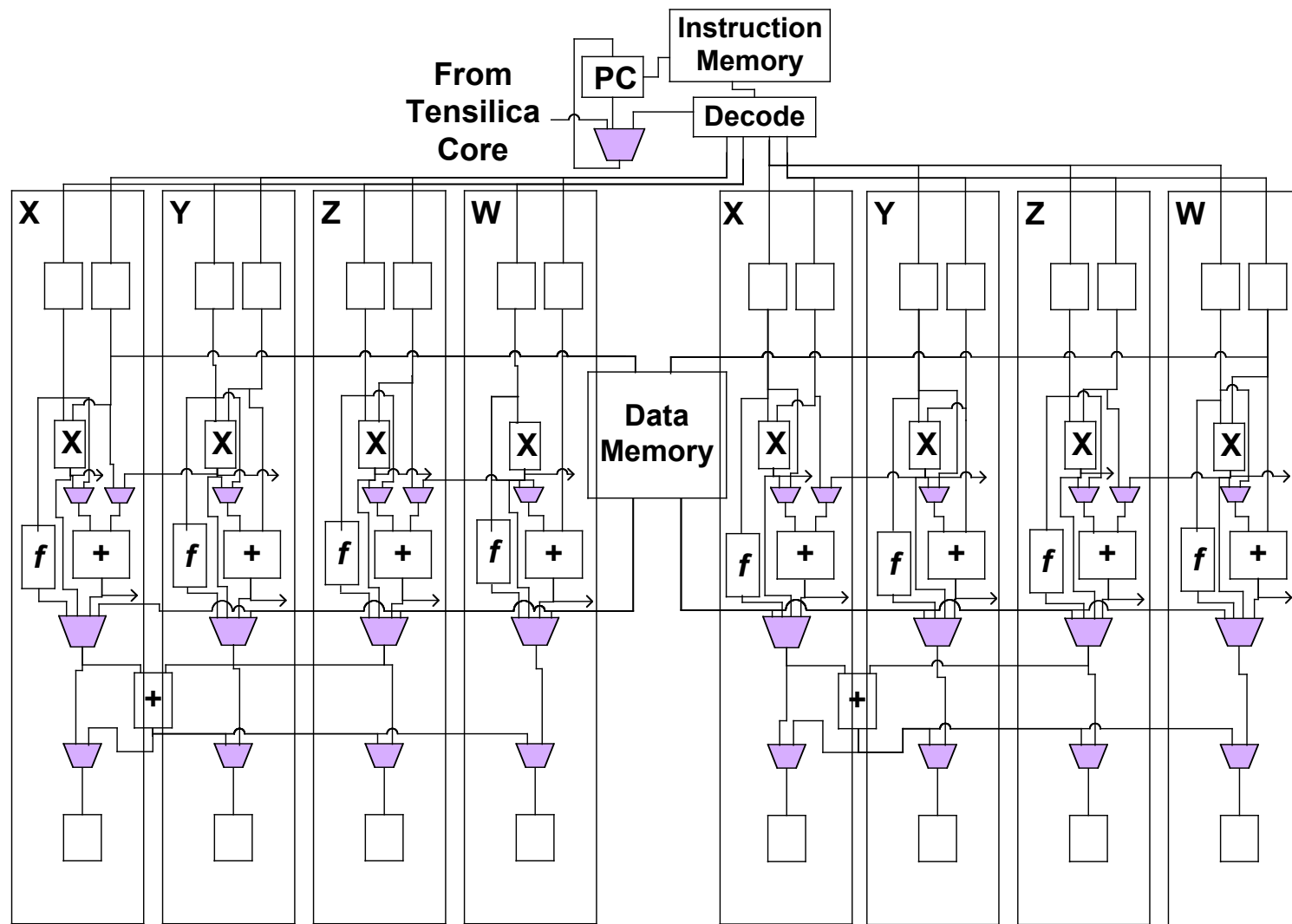
- The Flexible Subsystem exploits three forms of parallelism:
 - _ Multi-core parallelism (4 Tensilicas, 8 Geometry Cores)
 - _ Instruction-level parallelism
 - _ SIMD parallelism _ calculate on 3D and 4D vectors as single operation

Overview of the Flexible Subsystem



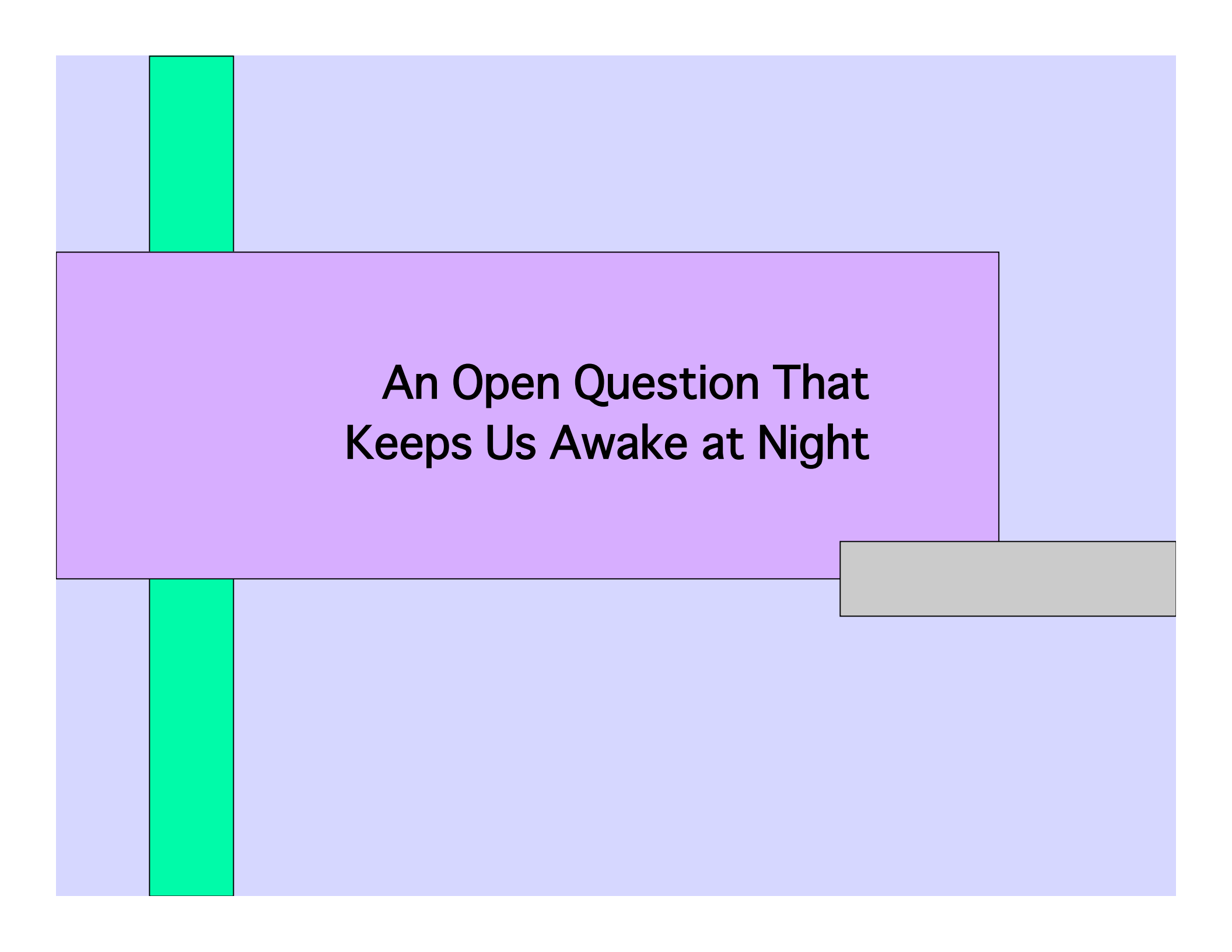
Geometry Core

(one of 8; 64 pipelined lanes/chip)



But Communication is Still a Bottleneck

- Scalability limited by inter-chip communication
- To execute a *single* millisecond-scale simulation,
 - Need a huge number of processing elements
 - Must dramatically reduce amount of data transferred between these processing elements
- Can't do this without fundamentally new algorithms:
 - A family of *Neutral Territory (NT) methods* that reduce pair interaction communication load significantly
 - A new variant of Ewald distant method, *Gaussian Split Ewald (GSE)* which simplifies calculation and communication for distant interactions
 - *These are the subject of a different talk.*



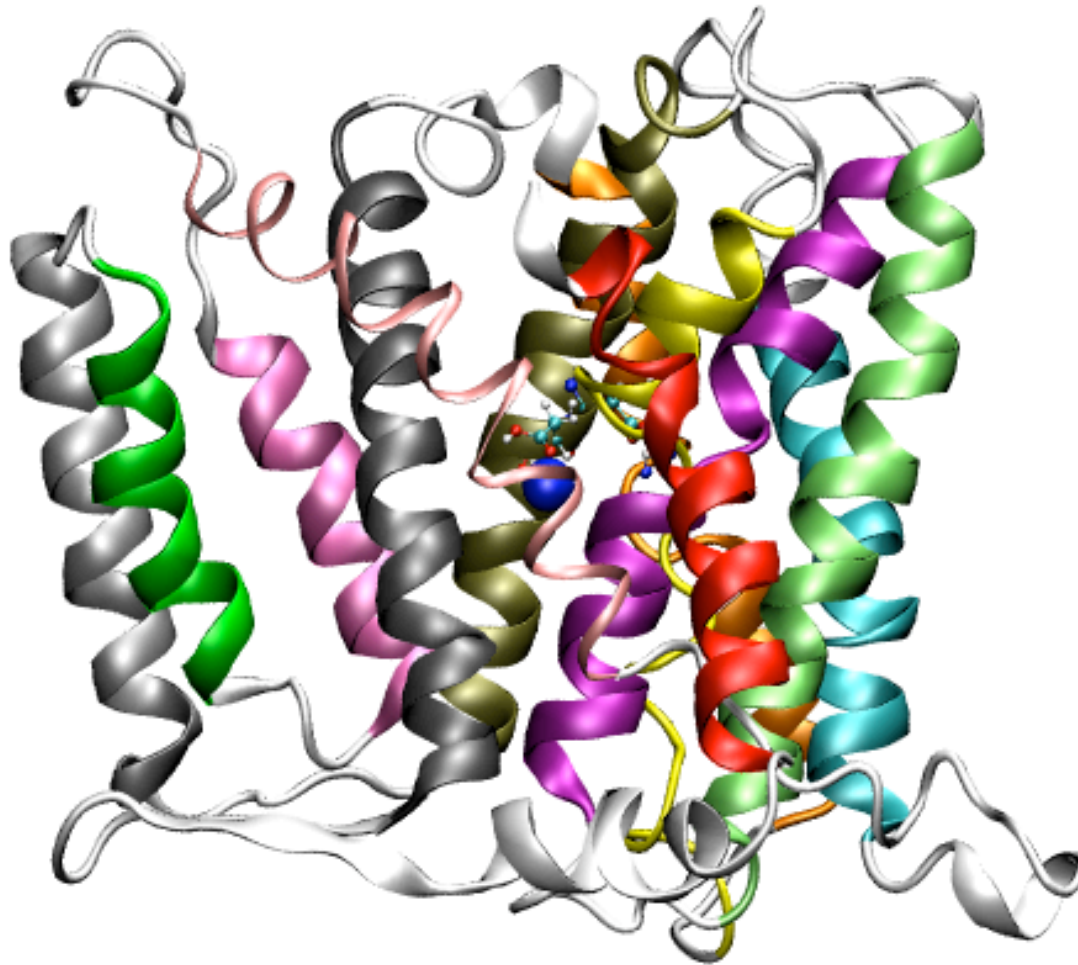
**An Open Question That
Keeps Us Awake at Night**

Are Force Fields Accurate Enough?

- Nobody knows how accurate the force fields that everyone uses actually are
 - _ Can' t simulate for long enough to know (*until we use Anton for the first time!*)
 - _ If problems surface, we should at least be able to
 - Figure out why
 - Take steps to fix them
- But we already know that fast, single MD simulations will prove sufficient to answer at least some major scientific questions

Example: Simulation of a Na⁺/H⁺ Antiporter

Cytoplasm



Periplasm

Our Functional Model of the Na^+/H^+ Antiporter

